

# Massive Scalar Polarizations of Gravitational Waves

# Background Knowledge: Polarizations

- ▶ Travelling oscillations of gravitational field.
- ▶ Gravitational wave polarizations can be thought of as components of gravitational waves.
- ▶ Green: Tensor
- ▶ Red: Vector
- ▶ Black: Scalar
- ▶ ([Sathyaprakash](#) and [Isi](#))

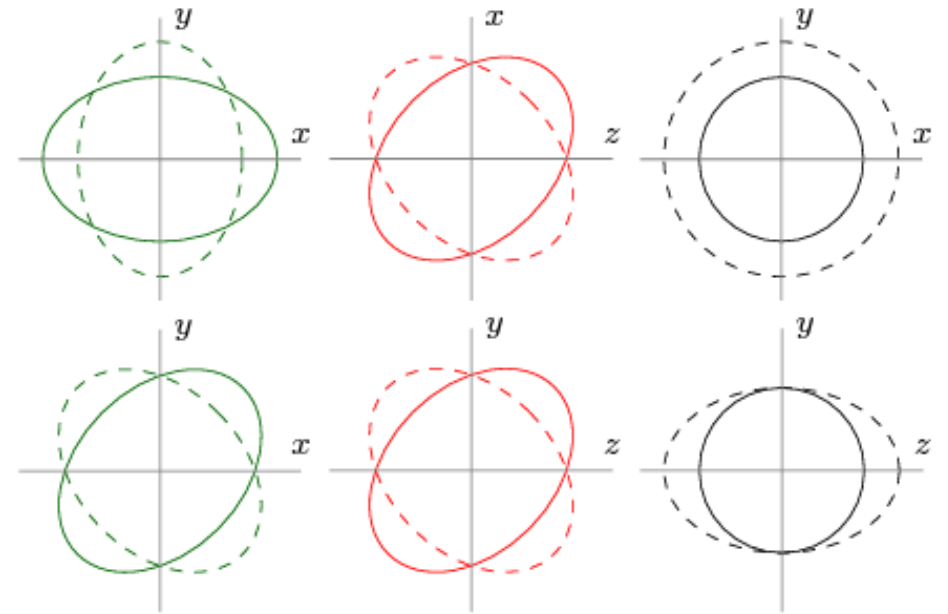


Figure Source: [Isi](#)

# Background Knowledge: Polarizations

- ▶ GR predicts massless gravitational waves and rejects non-tensor polarizations.
- ▶ There can also be scalar polarizations of gravitational waves, which is massive, in other theories.
- ▶ Massless: graviton has no mass, travels in the speed of light
- ▶ Massive: graviton has a mass, travels in a speed slower than the speed of light and depends on frequency.
- ▶ ([Isi](#), [Will](#) and [Yang](#))

# Background Knowledge: Polarizations

- ▶ Call the hypothesis having both massive scalar and massless tensor polarizations as the scalar-tensor hypothesis (as opposed to GR).

# Background knowledge: Polarizations

- ▶ Speed of massive scalar polarizations are given by,
- ▶ 
$$\frac{v_g^2}{c^2} = 1 - \frac{m_g^2 c^4}{h^2 f^2}$$
- ▶ Where  $m_g$  and  $f$  is the rest mass and the frequency of the graviton, respectively.
- ▶ The higher the frequency, the faster the massive scalar polarization (dispersion).
- ▶ The different traveling speed causes a time delay.
- ▶ ([Will](#) and [Yang](#))

# Aim

- ▶ To test how likely there are scalar polarizations supported by existing data.
- ▶ By looking at the time delay between the massless tensor polarizations and massive scalar polarizations of gravitational wave signals from binary black holes (BBHs).
- ▶  $P(H_{ST} | \{\Delta t_i\})$
- ▶  $\{\Delta t_i\}$  is the set of time differences between signal arrivals.

# Things to try suggested by supervisor

- ▶  $P(H_{ST} | \{\Delta t_i\}) \propto P(\{\Delta t_i\} | H_{ST})P(H_{ST})$
- ▶ Obtain samples of time delays of twin signals  $\Delta t_{TS}$ . (Tensor then Scalar)
- ▶ A twin signal is the pair of tensor signal and scalar signal from the same source.
- ▶ With samples of  $\Delta t_{TS}$ , by simulating time of arrivals of tensor signals, signals of tensor scalar polarizations can be obtained, thus getting  $P(\{\Delta t_i\} | H_{ST})$

# Time Delay Samples

- ▶ To get time delay samples, a population of BBHs may be simulated.
- ▶ As  $\Delta t_{TS}$  is given by  $\Delta t_{TS}(m_g, f, D_L)$ , keeping  $m_g$  constant, the only parameters of BBHs required to be simulated is the luminosity distance  $D_L$  and the total masses ( $M = m_1 + m_2, m_1 \geq m_2$ ) of the BBHs.
- ▶ The total masses of BBHs are required because the frequency of GWs are changing w.r.t. time, so the  $f_{isco}$  is chosen to represent the signal.
- ▶ The goal is  $P(M)$  and  $P(D_L)$  so that we can have samples of  $M$  and  $D_L$  for samples of  $\Delta t_{TS}$ .



# Time Delay Samples (con't)

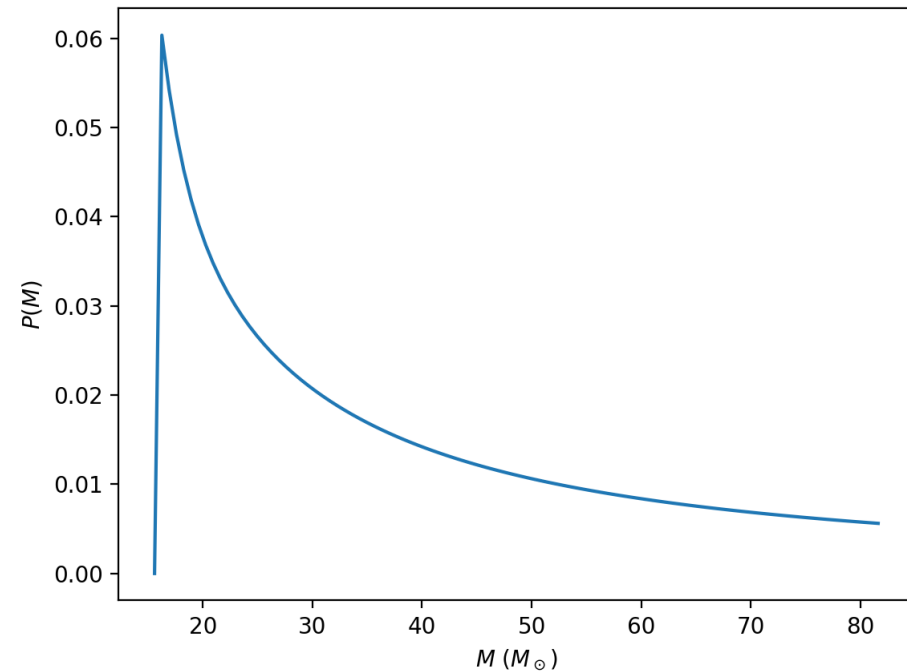
- ▶ The dependence of  $f_{isco}$  with the total mass  $M$  is,
- ▶  $f_{isco} = 4.4\left(\frac{M_{\odot}}{M}\right)\text{kHz}$
- ▶ We need the probability density distribution of  $m_1, m_2$  and  $D_L$  to get samples of them and hence samples of time delay  $\Delta t_{TS}$ .
- ▶ ([Veitch](#))

# Time Delay Samples: $P(m_1, m_2)$

- ▶  $P(m_1) = \left( \frac{1-\alpha}{m_{max}^{1-\alpha} - m_{min}^{1-\alpha}} \right) m_1^{-\alpha}$
- ▶  $P(m_2|m_1) = \left( \frac{1+\beta_q}{m_1^{1+\beta_q} - m_{min}^{1+\beta_q}} \right) m_1^{\beta_q} q^{\beta_q}$
- ▶  $P(m_1, m_2) = \left( \frac{1-\alpha}{m_{max}^{1-\alpha} - m_{min}^{1-\alpha}} \right) \left( \frac{1+\beta_q}{m_1^{1+\beta_q} - m_{min}^{1+\beta_q}} \right) m_1^{-\alpha+\beta_q} q^{\beta_q}$
- ▶ The primary mass and secondary mass (when given a primary mass) both follows a power law.
- ▶ The appearance of the mass ratio  $q = \frac{m_2}{m_1}$  in the distribution creates the tendency for the primary mass to be similar in magnitude to the secondary mass when  $\beta_q$  is positive ( $0 < q < 1$ ).
- ▶ ([Abbott](#))

# Time Delay Samples: $P(M)$

- ▶  $P(M)$  can be obtained by changing variable from  $(m_1, m_2)$  to  $(m_1, M)$  and then marginalizing over  $m_1$ .
- ▶ Doing the marginalization numerically,  $P(M)$



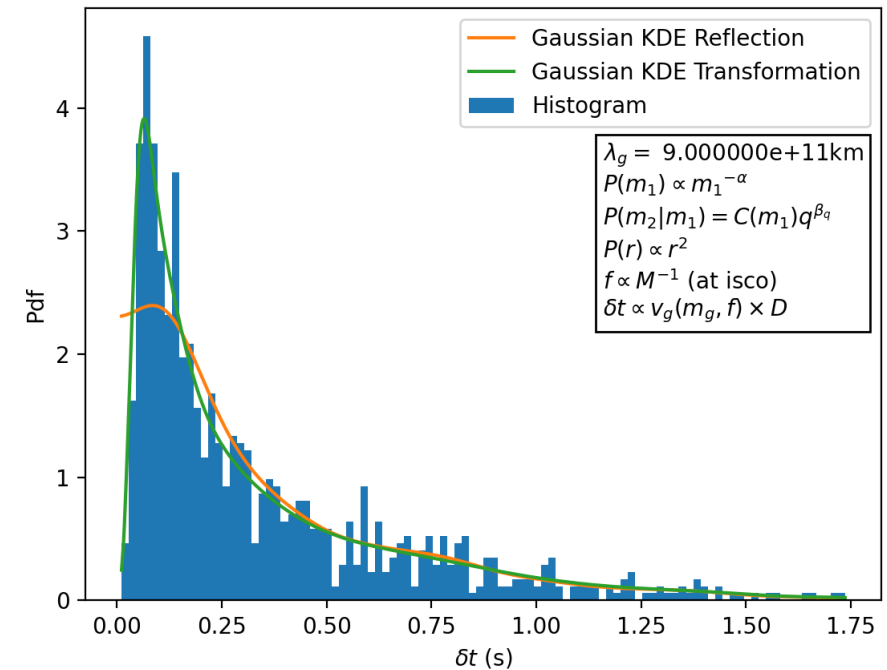
# Time Delay Samples: $P(D_L)$

- ▶ By the cosmological principle, the number of BBHs and hence the probability of having a BBH at luminosity distance  $D_L$  can be assumed to be proportional to the volume of a thin shell of the sphere at the distance

- ▶ 
$$P(D_L) = \frac{3D_L^2}{D_{Lmax}^3 - D_{Lmin}^3}$$

# Time Delay Samples

- By getting samples of  $M$  and  $D_L$  from their respective PDFs, samples of  $\Delta t_{TS}$  is obtained, and a Gaussian KDE is used to estimate  $P(\Delta t_{TS})$ .

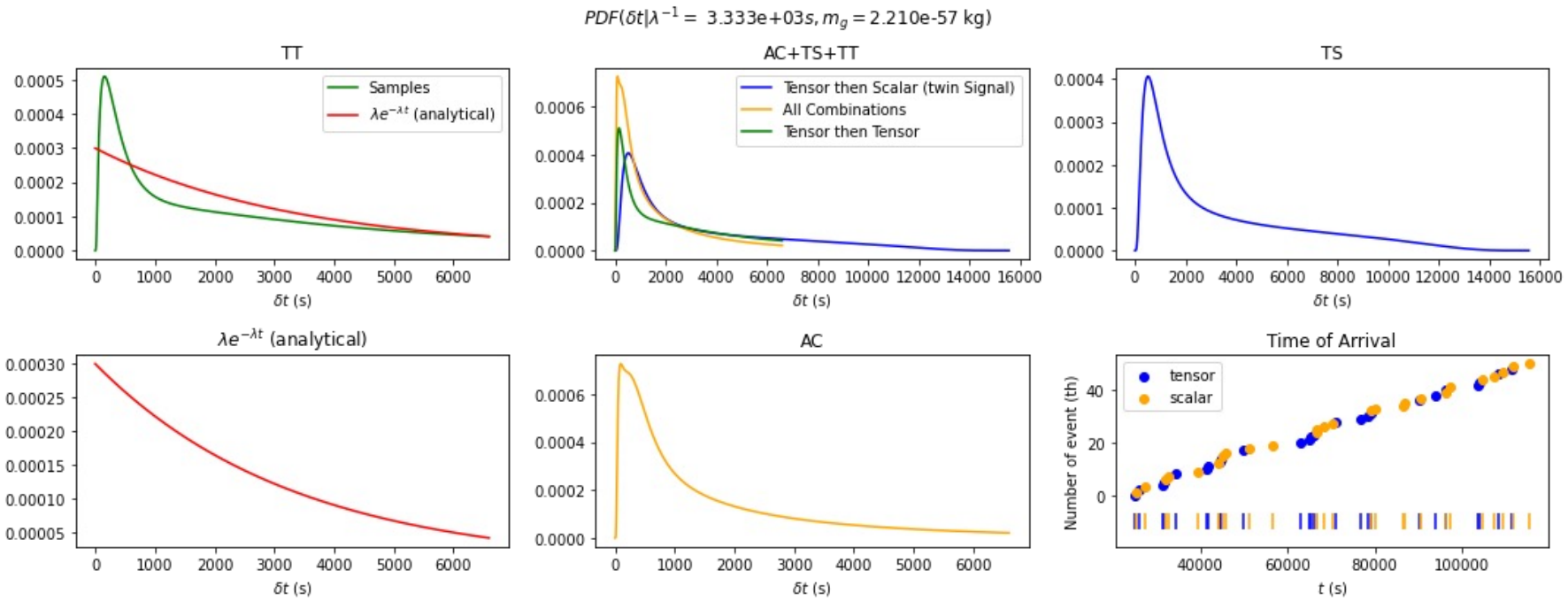


# Time Difference between All Signal Arrivals

- ▶ Define a time of detection.
- ▶ Generating tensor signals, then adding their corresponding twin scalar signals, and with scalar signals coming from earlier tensor signals, the signal arrival times with both polarizations can be simulated.
- ▶ How early in time tensor signals are generated equals to the maximum time delay (beyond the maximum time delay scalar twin signal do not arrive).

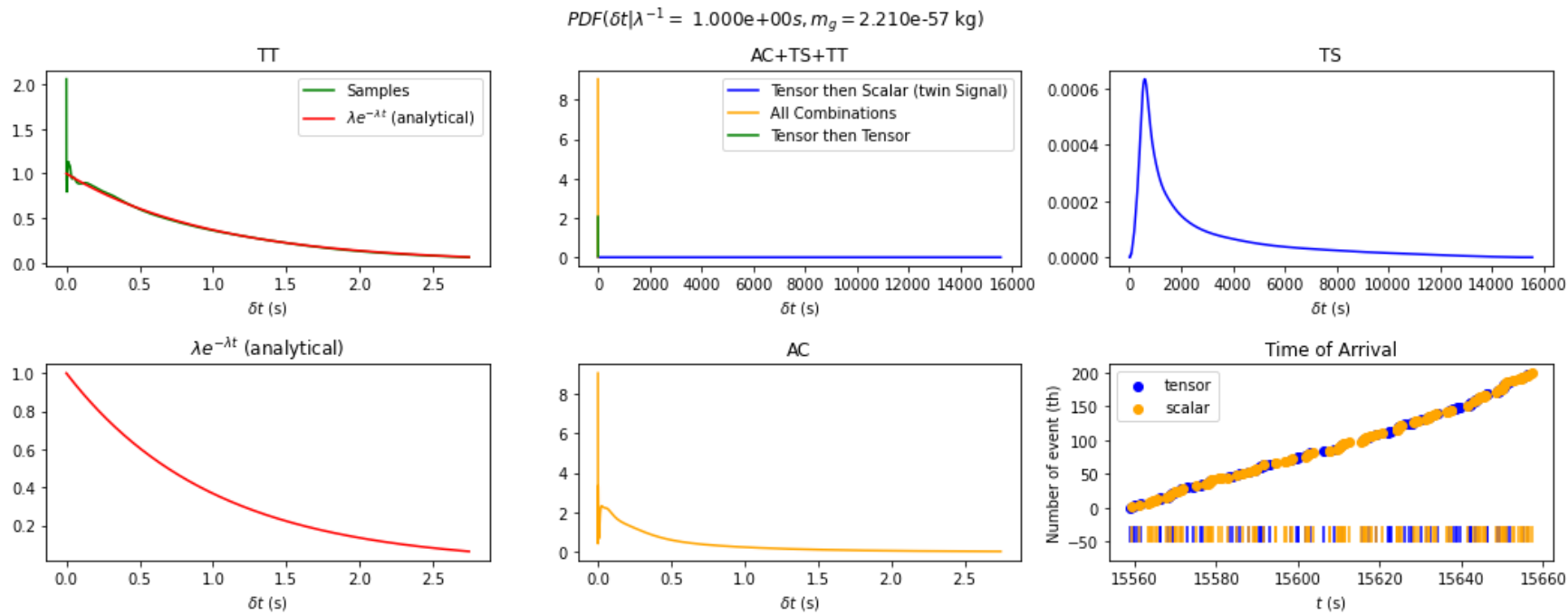
# Time Difference between All Signal Arrivals

- ▶ Tensor signals have to be first generated.
- ▶ Tensor signal arrival times can be modelled as a homogenous Poisson process,
- ▶  $P(n|\lambda) = \frac{(\lambda t)^n}{n!} e^{-\lambda t}$
- ▶ Because of the independence between events (and as the probability of receiving a signal scales with time).

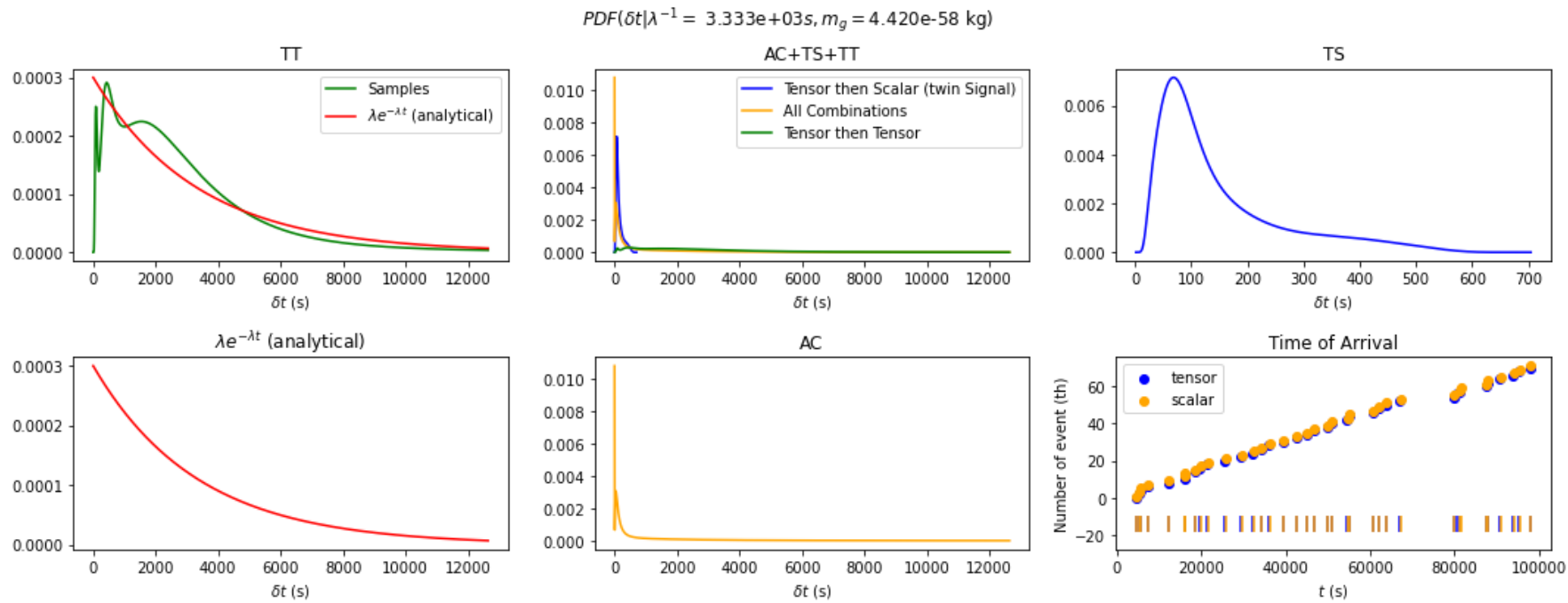


# Time Difference: TT~TS





# Time Difference: $TT < TS$



# Time Difference: $TT > TS$

# Acknowledgement

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