



EXTENDING SUPERCONFORMAL VECTOR FIELDS ON 6D SUPER-MINKOWSKI SPACETIME TO 10D

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MOTIVATION

- Why do we study conformal field theories (CFT)?
 - AdS/CFT correspondence and superstring theory



INTRODUCTION

BASIC ALGEBRA

- What is a group?
- What is a vector space?
- What is a Lie group?
- What is a Lie algebra?
- What is a representation?

GROUPS

A group (G, \circ) is a set G equipped with a binary operation $\circ : G \rightarrow G$ that satisfy three properties:

1. Associativity: $f \circ (g \circ h) = (f \circ g) \circ h$
2. Identity: $\exists e \in G$ such that $g \circ e = e \circ g = g \quad \forall g \in G$
3. Inverse: $\forall g \in G, \exists g^{-1}$ such that $g \circ g^{-1} = g^{-1} \circ g = e$

E.g. $(\mathbb{R}, +)$ and $(U(1), \cdot)$

- A Lie group is a group that is also a differentiable manifold, such that its group operation and inverse operation are smooth.

VECTOR SPACE

A real vector space is a set V equipped with a commutative binary operation (usually called addition) $+$: $V \times V \rightarrow V$ that makes $(V, +)$ into an abelian group, and a scalar multiplication \cdot : $\mathbb{R} \times V \rightarrow V$ that satisfies the following properties $\forall a, b \in \mathbb{R}$ and $\forall v, u \in V$:

1. $(a + b) \cdot v = a \cdot v + b \cdot v$

2. $a \cdot (v + u) = a \cdot v + a \cdot u$

3. $a \cdot (b \cdot v) = (ab) \cdot v$

4. $1 \cdot v = v$

E.g. $(\mathbb{R}^n, +, \cdot)$ and $(\mathbb{C}^n, +, \cdot)$

REPRESENTATIONS

- Homomorphisms are structure preserving maps.

$$\rho : G \rightarrow G'$$

$$\rho(gh) = \rho(g)\rho(h)$$

$$\rho(e) = e'$$

- Let A be some algebraic structure (group, algebra, etc). Then a representation of A is a homomorphism $\rho: A \rightarrow \text{Gl}(V)$, where V is some vector space. $\text{Gl}(V)$ is the group of isomorphism from V to itself.

LIE ALGEBRA (*ABSTRACT*)

A real Lie algebra is a real vector space V with a binary operation (called a Lie bracket) $[\cdot, \cdot] : V \times V \rightarrow V$ that satisfy three properties $\forall u, v, w \in V$ and $\forall r \in \mathbb{R}$:

1. $[u, v] = -[v, u]$
2. $[ru + v, w] = r[u, w] + [v, w]$
3. $[u, [v, w]] = [[u, v], w] + [v, [u, w]]$

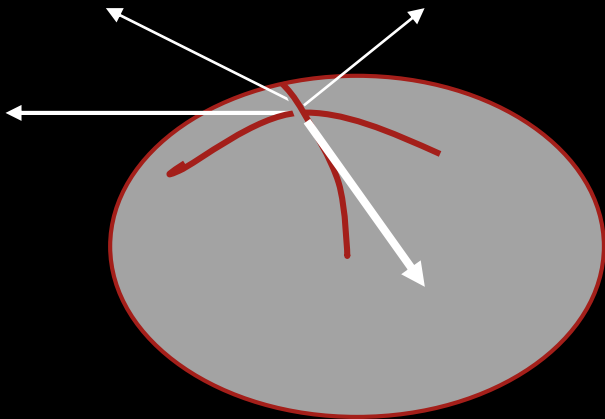
The third condition is called the Jacobi identity. It means that the Lie bracket makes the Lie algebra into a representation of itself.

EXAMPLES OF LIE ALGEBRA

1. The commutator $[a, b] := ab - ba$ together with $M_{n \times n}(\mathbb{R})$ or any matrix ring
2. The Poisson bracket in classical mechanics with the ring of all smooth functions $C^\infty(\mathbb{R}^{2n})$ on a phase space \mathbb{R}^{2n}
3. The commutator and the tangent vectors at the identity element of any Lie groups

LIE ALGEBRA OF A LIE GROUP

- Tangent vectors X at the identity element e of a Lie group G
- Related to the Lie group by the exponential map.



$$e^{tX} = \varphi(t),$$

Where $\varphi: I \rightarrow G$ is the unique curve satisfying $\varphi(0) = e$ and $\varphi'(0) = X$

LIE SUPERALGEBRA

A real Lie superalgebra is a \mathbb{Z}_2 -graded real associative algebra $A = A_0 \oplus A_1$ with a graded derivation (called the superbracket) $[\cdot, \cdot] : A \times A \rightarrow A$ satisfying the properties:

1. If $a_i \in A_i$ and $a_j \in A_j$ for some $i, j \in \{0, 1\}$, then $a_i a_j \in A_{(i+j) \bmod 2}$
2. If $a_0 \in A_0$, then $a_0 b = b a_0 \forall b \in A$
3. If $a_1, b_1 \in A_1$, then $a_1 b_1 = -b_1 a_1$
4. $[a, b] = -(-1)^{|a| \cdot |b|} [b, a]$, where $|x| = 0$ if $x \in A_0$ and $|x| = 1$ if $x \in A_1$
5. $(-1)^{|a| \cdot |c|} [a, [b, c]] + (-1)^{|b| \cdot |a|} [b, [c, a]] + (-1)^{|b| \cdot |c|} [c, [a, b]] = 0$

- Fact: The even part of a Lie superalgebra forms an ordinary Lie algebra.

CLIFFORD ALGEBRA

A standard real Clifford algebra $\mathcal{C}_{t,s}$ is a unital associative real algebra freely generated by the set $V = \{e_0, e_1, \dots, e_{t+s-1}\}$ such that

$$e_i e_j + e_j e_i = 2\eta_{ij} 1 \quad \forall i, j \in \{1, \dots, n\}, \text{ where } \eta_{ij} = \begin{cases} 0 & \text{if } i \neq j \\ -1 & \text{if } 0 \leq i = j \leq t-1 \\ 1 & \text{if } t \leq i = j \leq t+s-1 \end{cases}$$

Hence, $\mathcal{C}_{t,s} = \text{span}\{1, e_0, \dots, e_{s+t-1}, e_0 e_1, \dots, e_0 \dots e_{s+t-1}\}$

CLIFFORD ALGEBRA

- Why do we care? Because it is a representation of the **Lorentz group**
- It is a superalgebra
- Example: Pauli matrices (a basis for $su(2)$)

$$\tilde{\sigma}^0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \tilde{\sigma}^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \tilde{\sigma}^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \tilde{\sigma}^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

In higher dimension, we have sigma matrices (will be shown later) that are built from Pauli matrices.

CLASSIFICATION OF CLIFFORD ALGEBRA

$t - s \text{ mod. } 8$	$\mathcal{C}_{t,s}$
0	$\mathcal{M}_{2\ell}(\mathbb{R})$
1	$\mathcal{M}_{2\ell}(\mathbb{R}) \oplus \mathcal{M}_{2\ell}(\mathbb{R})$
2	$\mathcal{M}_{2\ell}(\mathbb{R})$
3	$\mathcal{M}_{2\ell}(\mathbb{C})$
4	$\mathcal{M}_{2\ell-1}(\mathbb{H})$
5	$\mathcal{M}_{2\ell-1}(\mathbb{H}) \oplus \mathcal{M}_{2\ell-1}(\mathbb{H})$
6	$\mathcal{M}_{2\ell-1}(\mathbb{H})$
7	$\mathcal{M}_{2\ell}(\mathbb{C})$

Taken from [Rausch de Traubenberg](#)'s "Clifford Algebra in Physics"

POINCARÉ GROUP

- Lorentz group: Homogeneous part of the Poincaré group.

$$x' = Ax + c$$

- Poincaré group: Isometry group of Minkowski spacetime, i.e. infinitesimal automorphisms (symmetries) that keep the metric tensor invariant.

$$\mathcal{L}_X g = 0 \iff \partial_\mu X_\nu + \partial_\nu X_\mu = 0$$

- In our 4D spacetime, its identity component is $5(4)/2=10$ dimensional (as a manifold).

$$ISO(1, d-1) = \mathbb{R}^d \rtimes O(1, d-1)$$

$$\mathfrak{iso}(\mathbb{R}^{1, d-1}) = \mathbb{R}^d \oplus \mathfrak{so}(1, d-1)$$

CONFORMAL GROUP

- Angle-preserving transformations, an extension of the Poincaré group

$$x^\mu \rightarrow x^\mu + \xi^\mu$$

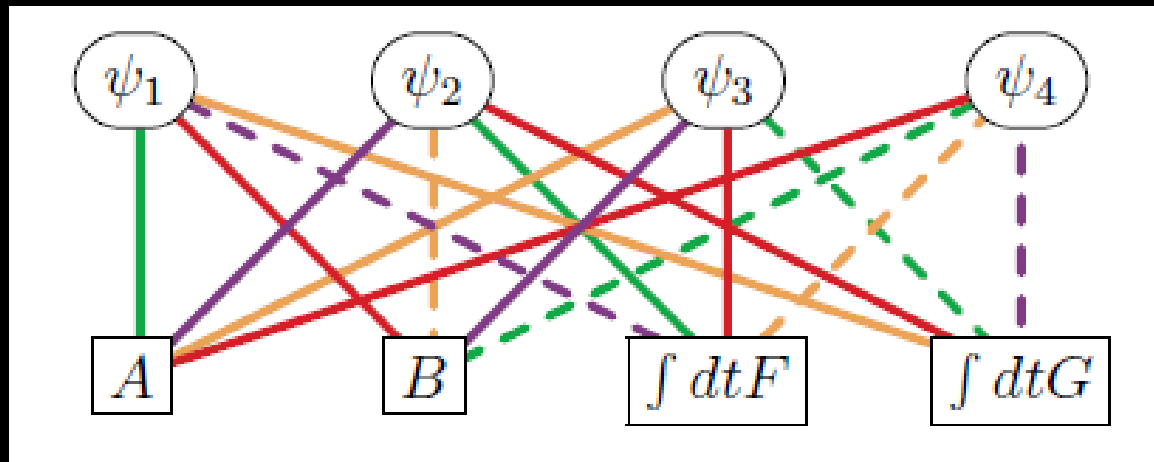
$$\partial_\mu \xi_\nu + \partial_\nu \xi_\mu = \frac{2}{d} \eta_{\mu\nu} \partial \cdot \xi \quad \text{where } \partial \cdot \xi = \partial^\rho \xi_\rho.$$

- Conformal algebra (group) isomorphic to SO algebra (group)
- $\text{Conf}(1, d-1) \sim \text{SO}(2, d) \sim \text{AdS}(d+1)$, the $d+1$ Lorentzian Anti-de-Sitter space embedded as a surface in the $d+2$ D spacetime.

$$\text{conf}(1, d - 1) \simeq \text{so}(2, d)$$

SUPERSYMMETRY

- Coleman-Mandula Theorem: Symmetry group of a 4D QFT can only have Poincaré group and internal symmetries.
- Haag-Lopuszanski-Sohnius Theorem: We can have anticommuting symmetries too!
- Transformation between bosons and fermions



Adinkra, taken from Gates et al, "Adinkra Height Yielding Matrix Numbers: Eigenvalue Equivalence Classes for Minimal Four-Color Adinkras"

SUPERSPACE (SUPERMANIFOLDS)

The ordinary Minkowski spacetime can be recovered by

$$\mathbb{R}^{1,d-1} \simeq \text{iso}(\mathbb{R}^{1,d-1}) / \text{so}(1, d-1)$$

We can imagine a Minkowski superspace defined as above but replace the Poincaré algebra by Super-Poincaré algebra, which is a superalgebra that contains the Poincaré algebra as its even part.

The topology of supermanifolds is weird, e.g. not Hausdorff, and integration=differentiation

GRASSMANN NUMBERS

- Objects that anticommute:

$$\theta_i \theta_j = -\theta_j \theta_i$$

- Mathematically, the Grassmann algebra generated by a complex vector space V is

$$\Lambda(V) := \mathbb{C} \oplus \Lambda^1 V \oplus \Lambda^2 V \oplus \dots \oplus \Lambda^n V$$

where $\Lambda^2 V = V \wedge V$ and $n := \dim_{\mathbb{C}}(V)$

- On a super-Minkowski space, we have ordinary (bosonic) spacetime coordinates x^a and anticommuting (fermionic) coordinates θ^α



SUPERCONFORMAL VECTOR FIELDS

WHAT DO WE WANT?

1. A representation of some superalgebra that acts as infinitesimal automorphism on super-Minkowski space, i.e. vector field representations, that is
2. An extension of the super- Poincaré algebra, and
3. When its even (bosonic) part's action is restricted on ordinary Minkowski space, it reduces to the ordinary conformal algebra $so(2,d)$

SUPER-POINCARÉ ALGEBRA

$$P_a = \partial_a$$

$$M_{ab} = -\frac{1}{2}x_a\partial_b + \frac{1}{2}x_b\partial_a - \frac{1}{4}\theta^\beta(\sigma_{ab})_\beta^\alpha\partial_\alpha$$

$$Q_\alpha = \partial_\alpha - \frac{1}{2}\theta^\beta(\sigma^a)_{\alpha\beta}\partial_a$$

$$[P_a, M_{bc}] = -\eta_{a[b}P_{c]}$$

$$[M_{ab}, M_{cd}] = \eta_{c[a}M_{b]d} - \eta_{d[a}M_{b]c}$$

$$[M_{ab}, Q_\alpha] = \frac{1}{4}(\sigma_{ab})_\alpha^\beta Q_\beta$$

Generated by translation, Lorentz rotation, and supercharge Q

5+1D CONFORMAL VECTOR FIELDS

$$D = x \cdot \partial + \frac{1}{2} \theta \cdot \partial$$

$$P_a = \partial_a$$

$$M_{ab} = -\frac{1}{2} x_a \partial_b + \frac{1}{2} x_b \partial_a - \frac{1}{4} \theta_c^\beta (\sigma_{ab})_\beta^\alpha \partial_\alpha^c$$

$$K_a = x^2 \partial_a - 2x_a x \cdot \partial + \frac{1}{4} (\sigma_a)_{\beta\alpha} \theta^\alpha \cdot \theta^\gamma \theta^\beta \cdot \theta^\delta (\sigma_b)_{\gamma\delta} \partial_b - x_a \theta \cdot \partial$$

$$- x^b \theta_c^\alpha (\sigma_{ab})_\alpha^\gamma \partial_\gamma^c + i (\sigma_a)_{\beta\alpha} \theta_c^\alpha \theta^\beta \cdot \theta^\gamma \partial_\gamma^c$$

Dilation, translation, Lorentz transformation, special conformal transformation

CONFORMAL ALGEBRA

$$[P_a, M_{bc}] = -\eta_{a[b}P_{c]}$$

$$[K_a, D] = -K_a$$

$$[P_a, D] = P_a$$

$$[K_a, M_{bc}] = -\eta_{a[b}K_{c]}$$

$$[M_{ab}, M_{cd}] = \eta_{c[a}M_{b]d} - \eta_{d[a}M_{b]c}$$

$$[P_a, K_b] = -4M_{ab} - 2\eta_{ab}D$$

This is true for all dimension >2 ! The indices may come from any range.

FERMIONIC VECTOR FIELDS

Q supercharge: the “square-root” of the translation P

$$Q_{\alpha}^a = \partial_{\alpha}^a - \frac{1}{2} i \Omega^{ac} \theta_c^{\gamma} (\sigma^b)_{\alpha\gamma} \partial_b$$

S supercharge: the “square-root” of the special conformal transformation K

$$S_a^{\alpha} = -\Omega_{ac} ((\sigma^b)^{\alpha\gamma} x_b + i\theta^{\alpha} \cdot \theta^{\gamma}) \partial_{\gamma}^c + 2i\theta_a^{\gamma} \theta_c^{\alpha} \partial_{\gamma}^c + \frac{1}{2} i x_b \theta_a^{\gamma} (\sigma^{db})_{\gamma}^{\alpha} \partial_d \\ + \frac{1}{2} i \theta_a^{\alpha} x \cdot \partial - \frac{1}{2} (\sigma^d)_{\gamma\delta} \theta_a^{\gamma} \theta^{\delta} \cdot \theta^{\alpha} \partial_d$$

$$\{S_a^\alpha, S_b^\beta\} = -2i\Omega_{ab}K^{\alpha\beta}$$

$$\{Q_\alpha^a, Q_\beta^b\} = -2i\Omega^{ab}P_{\alpha\beta}$$

where the R-symmetry invariant tensor satisfies $\Omega_{ab}\Omega^{bc} = \delta_a^c$.

$$\{Q_\alpha^a, S_b^\beta\} = i\delta_\alpha^\beta (\delta_b^a D - 4\Omega_{bc}U^{ac}) + 2i\delta_b^a M_\alpha^\beta$$

R- symmetry bosonic vector fields: U^{ab}

9+1D SPACETIME: SIGMA MATRICES

$$(\sigma^0)_{\alpha\beta} = \tilde{\sigma}^0 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^0,$$

$$(\sigma^1)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^2 \otimes \tilde{\sigma}^2 \otimes \tilde{\sigma}^2,$$

$$(\sigma^2)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^2 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^1,$$

$$(\sigma^3)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^2 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^1,$$

$$(\sigma^4)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^1 \otimes \tilde{\sigma}^2 \otimes \tilde{\sigma}^0,$$

$$(\sigma^5)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^3 \otimes \tilde{\sigma}^2 \otimes \tilde{\sigma}^0,$$

$$(\sigma^6)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^1 \otimes \tilde{\sigma}^2,$$

$$(\sigma^7)_{\alpha\beta} = \tilde{\sigma}^2 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^3 \otimes \tilde{\sigma}^2,$$

$$(\sigma^8)_{\alpha\beta} = \tilde{\sigma}^1 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^0,$$

$$(\sigma^9)_{\alpha\beta} = \tilde{\sigma}^3 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^0 \otimes \tilde{\sigma}^0$$

$$(\sigma^{ab})_{\alpha}{}^{\gamma} := (\sigma^{[a} \sigma^{b]})_{\alpha}{}^{\gamma},$$

$$(\sigma^{abc})_{\alpha\gamma} := (\sigma^{bc})_{\alpha}{}^{\beta} (\sigma^a)_{\beta\gamma} + 2\eta^{a[b} (\sigma^{c]})_{\alpha\gamma},$$

$$(\sigma^{abcd})_{\alpha}{}^{\gamma} := (\sigma^a)_{\alpha\beta} (\sigma^{bcd})^{\beta\gamma} - 3\eta^{a[b} (\sigma^{cd])_{\alpha}{}^{\gamma}},$$

$$(\sigma^{abcde})_{\alpha\gamma} := (\sigma^{bcde})_{\alpha}{}^{\beta} (\sigma^a)_{\beta\gamma} + 4\eta^{a[b} (\sigma^{cde])_{\alpha\gamma}$$

$$(\sigma^a)_{\alpha\beta} (\sigma^b)^{\beta\gamma} + (\sigma^b)_{\alpha\beta} (\sigma^a)^{\beta\gamma} = 2\eta^{ab} \delta_{\alpha}{}^{\gamma}$$

In 10D we have Majorana-Weyl spinors, hence the sigma matrices are 16 times 16 real matrices.

FIERZ IDENTITIES

$$(\sigma^b)_{\alpha[\beta}(\sigma_{ab})_{\gamma]}^{\delta} = \frac{5}{32}(\sigma^{[2]})_{\alpha}^{\delta}(\sigma_{a[2]})_{\beta\gamma} - \frac{1}{32}(\sigma_{a[3]})_{\alpha}^{\delta}(\sigma^{[3]})_{\beta\gamma}$$

$$(\sigma^{[3]}\sigma^a)_{\gamma}^{(\alpha}(\sigma_{[3]})^{\beta)\delta} = -3(\sigma_b)^{\alpha\beta}(\sigma^{ab})_{\gamma}^{\delta} + \frac{1}{8}(\sigma^{a[4]})^{\alpha\beta}(\sigma_{[4]})_{\gamma}^{\delta} - 45(\sigma^a)^{\alpha\beta}\delta_{\gamma}^{\delta}$$

$$(\sigma^{a[3]})_{[\delta}^{\alpha}(\sigma_{[3]})_{\beta]\gamma} = -\frac{1}{2}(\sigma_{[3]})_{\delta\beta}(\sigma^{a[3]})_{\gamma}^{\alpha}$$

$$(\sigma^{a[3]})_{\delta}^{[\alpha}(\sigma_{[3]})^{\beta]\gamma} = -\frac{1}{2}(\sigma_{[3]})^{\alpha\beta}(\sigma^{a[3]})_{\delta}^{\gamma}$$

$$(\sigma_{cde}\sigma_{ab})^{[\beta\alpha]} = 2\eta_{c[b}(\sigma_{a]de})^{\alpha\beta} - 2\eta_{d[b}(\sigma_{a]ce})^{\alpha\beta} + 2\eta_{e[b}(\sigma_{a]cd})^{\alpha\beta}$$

RESULTS

Proposition 1. *The generalized expression of S^α satisfying*

$$[S^\alpha, D] = -\frac{1}{2}S^\alpha, \quad (5.14)$$

$$[P_a, S^\alpha] = (\sigma^a)^{\alpha\beta}Q_\beta \quad (5.15)$$

is given by

$$S^\alpha = x^a(\sigma_a)^{\alpha\beta}Q_\beta + k_1\theta^\alpha\theta \cdot \partial + k_2(\sigma^{abc})_{\beta\gamma}(\sigma_{abc})^{\alpha\delta}\theta^\beta\theta^\gamma\partial_\delta + \\ k_3(\sigma^{abc})_{\beta\gamma}(\sigma_{bc})_\delta^\alpha\theta^\delta\theta^\beta\theta^\gamma\partial_a + k_4(\sigma_{bcd})_{\beta\gamma}(\sigma^{abcd})_\delta^\alpha\theta^\delta\theta^\beta\theta^\gamma\partial_a \quad (5.16)$$

Proposition 2. *Suppose that $[K_a, D] = -K_a$, then*

$$K_a = x^2\partial_a - 2x_ax \cdot \partial + c_1x_a\theta \cdot \partial + c_2x^b\theta^\alpha(\sigma_{ab})_\alpha^\beta\partial_\beta + c_3\theta^\alpha\theta^\beta\theta^\gamma(\sigma^{[3]})_{\alpha\beta}(\sigma_{a[3]})_\gamma^\delta\partial_\delta + c_4\theta^\alpha\theta^\beta\theta^\gamma(\sigma_{a[2]})_{\alpha\beta}(\sigma^{[2]})_\gamma^\delta\partial_\delta \\ + c_5x_b\theta^\alpha\theta^\beta(\sigma_a^{bc})_{\alpha\beta}\partial_c + c_6\theta^\alpha\theta^\beta\theta^\gamma\theta^\delta(\sigma_{[3]})_{\alpha\beta}(\sigma^{[3]})_{\gamma\delta}\partial_a + c_7\theta^\alpha\theta^\beta\theta^\gamma\theta^\delta(\sigma_{a[2]})_{\alpha\beta}(\sigma^{[2]b})_{\gamma\delta}\partial_b \quad (5.27)$$

where $c_1, \dots, c_7 \in \mathbb{C}$.

Lemma 4.5 (Siew).

$$\theta^\alpha \theta^\beta \theta^\gamma (\sigma_{a[3]})_{\gamma}{}^\delta (\sigma^{[3]})_{\alpha\beta} = 0$$

$$\theta^\alpha \theta^\beta \theta^\gamma (\sigma_{a[2]})_{\alpha\beta} (\sigma^{[2]})_{\gamma}{}^\delta = 0$$

$$\theta^\alpha \theta^\beta \theta^\gamma \theta^\delta (\sigma_{[3]})_{\alpha\beta} (\sigma^{[3]})_{\gamma\delta} = 0$$

$$\theta^\alpha \theta^\beta \theta^\gamma \theta^\delta (\sigma_{a[2]})_{\alpha\beta} (\sigma^{[2]b})_{\gamma\delta} = 0$$

Corollary 4.5.1. *We can shorten the results of Proposition 1 and Proposition 2 to*

$$S^\alpha = x^a (\sigma_a)^{\alpha\beta} Q_\beta + k_1 \theta^\alpha \theta \cdot \partial + k_2 (\sigma^{abc})_{\beta\gamma} (\sigma_{abc})^{\alpha\delta} \theta^\beta \theta^\gamma \partial_\delta$$

$$K_a = x^2 \partial_a - 2x_a x \cdot \partial + c_1 x_a \theta \cdot \partial + c_2 x^b \theta^\alpha (\sigma_{ab})_\alpha{}^\beta \partial_\beta + c_3 x_b \theta^\alpha \theta^\beta (\sigma_a{}^{bc})_{\alpha\beta} \partial_c.$$

Theorem 4.1. *Let $Q_\alpha = \partial_\alpha + k_1(\sigma^a)_{\alpha\beta}\theta^\beta\partial_a$ and $K_a = x^2\partial_a - 2x_ax \cdot \partial + c_1x_a\theta \cdot \partial + c_2x^b\theta^\alpha(\sigma_{ab})_\alpha^\beta\partial_\beta + c_3x_b\theta^\alpha\theta^\beta(\sigma_a^{bc})_{\alpha\beta}\partial_c$ for some constants k_1, c_1, c_2, c_3 such that $k_1 \neq 0$. Then $\forall k \in \mathbb{C} \setminus \{0\} : [Q_\alpha, K_a] \neq k(\sigma_a)_{\alpha\beta}S^\beta$.*

- Now relax the conditions... Only require S to be a “square-root” of K .

Lemma 5.1. *Suppose S^α is a fermionic vector field with units of \sqrt{x} . Then,*

$$S^\alpha = b_1\theta^\alpha x \cdot \partial + b_2x_a(\sigma^{ab})_\beta^\alpha\theta^\beta\partial_b + b_3\theta^\alpha\theta \cdot \partial + b_4\theta^\beta\theta^\gamma(\sigma^{[3]})_{\beta\gamma}(\sigma_{[3]})^{\alpha\delta}\partial_\delta + b_5x^a(\sigma_a)^{\alpha\beta}\partial_\beta$$

for some constants $b_1, b_2, b_3, b_4, b_5 \in \mathbb{R}$.

NON-EXISTENCE OF S SUPERCHARGE

Theorem 5.1. Suppose there is a bosonic vector field $K_a = x^2 \partial_a - 2x_a x \cdot \partial + c_1 x_a \theta \cdot \partial + c_2 x^b \theta^\alpha (\sigma_{ab})_\alpha^\beta \partial_\beta + c_3 x_b \theta^\alpha \theta^\beta (\sigma_a^{bc})_{\alpha\beta} \partial_c$ for some $c_1, c_2, c_3 \in \mathbb{R}$. Then, $\{S^\alpha, S^\beta\} \neq k(\sigma^a)^{\alpha\beta} K_a \quad \forall k \in \mathbb{R} \setminus \{0\}$.

This result is expected : According to Shnider's "The Superconformal Algebra in Higher Dimensions", superconformal algebras do not exist in **even dimensions $d > 6$** .

This is the first constructive proof that shows exactly why it does not exist in 10D.

FUTURE RESEARCH DIRECTION

- Extend the analysis to $10+1D$, where superconformal algebra is not forbidden by the no-go theorem mentioned before
- At the same time, another on-going project: Using Breitenlohner's method to investigate supergravity.

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