

Weak Gravitational Lensing Take a closer and wider look of our universe

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Overview

- Theory and Background (Weak Gravitational Lensing)
- Methods (LSST pipeline)
- Result (Mass Distribution)
- Conclusion

Theory and Background

- What is weak lensing?
- Theoretical proposal of weak lensing measurement.
- Advantage of the method.
- Possible sources of error.



Artist interpretation of Gravitational Lensing [1]



• Simulation of the effect of gravitational lensing. Left is weak gravitational lensing, right is strong gravitational lensing. "Real sources are not in a plane, but this does not dramatically affect the appearance." Image by David Wittman [2]



Figure 2.2: Distortion effects due to convergence and shear on a circular source (Figure from Narayan & Bartelmann, 1995). [3]



$$\kappa(r) = rac{\Sigma(r)}{\Sigma_{crit}}$$
, $\sum_{crit} = rac{c^2}{4\pi G} rac{D_L D_S}{D_{LS}}$

In weak gravitational lensing regime:

$$\langle e_t \rangle = \left\langle \frac{\gamma_t}{1-\kappa} \right\rangle \approx \langle \gamma_t \rangle$$
 , when $\kappa \ll 1$

under the assumption that the background is randomly oriented.

Radial Densitometry:

$$\bar{\kappa}(< r_1) - \bar{\kappa}(r_1 < r < r_2) = \frac{2}{1 - \frac{r_1^2}{r_2^2}} \int_{r_1}^{r_2} \frac{\langle \gamma_t(r) \rangle}{1 - \kappa(r)} d\ln r$$





conceptual picture of 1D convergence reconstruction

Possible sources of error

- Shape noise
- Intrinsic Alignment
- PSF anisotropy
- Atmosphere turbulence
- •

Imaging – Subaru Telescope w/ Hyper Suprime-Cam



Subaru Telescope Effective diameter: 8.2 m Focal length: 15 m



Hyper Suprime-Cam (HSC) model



Sensor: 116 2kx4k CCDs Diameter: 60 cm Resolution: 870 Megapixels

Combine the sensor & the telescope FOV: 1.8 deg²

Methods (LSST pipeline)



- Release Notes
- Characterization Metric Report



LSST image processing flow chart [4]

Pipeline

- 1. Making Calibration Frames (Bias, Dark, Flat Frame)
- 2. Reduction for each image for one filter
- 3. Mosaicing
- 4. Stacking
- 5. Multiband Analysis
- OUTPUT catalog

Calibration Frames

- Dark Frame: Measuring thermal noise for each sensor
- Bias Frame: Measuring the response of sensors
- Flat Frame: Calibrating the even dispersion of light by lens (telescope)

Raw Data





One of the CCD raw image of A85.

All raw data retrieved from SMOKA.

Reduction for each image for one filter

1)Single Visit Processing



Single Visit Processing [4]

conceptual PSF [5]



The Pan-STARRS1 data archive home page



Welcome to the starting point for access to data from the Panoramic Survey Telescope and Rapid Response System (Pan-STARRS). This page provides a brief summary of the facilities and data products to guide Pan-STARRS archive users. More complete information is provided on linked pages (see below)

Pan-STARRS is a system for wide-field astronomical imaging developed and operated by the Pan-STARRS Institute for Astronomy at the University of Hawaii. Pan-STARRS1 (PS1) is the first part of Pan-STARRS to be completed and is the basis for Data Release 1 (DR1). The PS1 survey cope and its 1.4 Gigapixel camera (GPC1; see PS1 GPC1 camera) to image the sky in five broadband

filters (g, r, i, z, y). The PS1 Science Consortium funded the operation of the Pan-STARRS1 telescope, situated at Haleakala Observatories near the summit of Haleakala in Hawaii, for the purposes of astronomical research. The PS1 consortium is made up of astronomers and engineers from 14 institutions from six countries

The data from PS1 are archived at the Space Telescope Science Institute (STScI) in Baltimore Maryland, and can be accessed through MAST, the Mikulski Archive for Space Telescopes. Additional support for the PS1 public science archive is provided by the Gordon and Betty Moore Foundation

The web site for Pan-STARRS1 in Hawaii also describes the project.

Quick links to the MAST PS1 Archive User Interface

Use the following links to jump right to the MAST PS1 Science Archive interfaces and get started using PS1 data!

Object Catalog Search: http://archive.stsci.edu/panstarrs/search.php





· 2017.02.02: PS1 sky available in MAST Portal

Papers describing the instrument, survey, and data

Mosaicing



Stacking



Multiband Analysis

• Final calibration between different broad-band filters (g, r, i, z, Y)



Catalog

• output a catalog with measurements

id: unique ID coord ra: position in ra/dec coord dec: position in ra/dec parent: unique ID of parent source calib detected: Source was detected as an icSource calib psfCandidate: Flag set if the source was a candidate for PSF determination, as determined by the star selector. calib psfUsed: Flag set if the source was actually used for PSF determination, as determined by the calib psfReserved: Flag set if the source was selected as a PSF candidate, but was reserved from the PSF fitting. deblend nChild: Number of children this object has (defaults to 0) deblend_deblendedAsPsf: Deblender thought this source looked like a PSF deblend psfCenter x: If deblended-as-psf, the PSF centroid deblend psfCenter y: If deblended-as-psf, the PSF centroid deblend psfFlux: If deblended-as-psf, the PSF flux deblend tooManyPeaks: Source had too many peaks; only the brightest were included deblend_parentTooBig: Parent footprint covered too many pixels deblend masked: Parent footprint was predominantly masked deblend skipped: Deblender skipped this source deblend rampedTemplate: This source was near an image edge and the deblender used "ramp" edge-handling. deblend_patchedTemplate: This source was near an image edge and the deblender used "patched" edge-handling. deblend hasStrayFlux: This source was assigned some stray flux base_GaussianCentroid_x: centroid from Gaussian Centroid algorithm base GaussianCentroid y: centroid from Gaussian Centroid algorithm base NaiveCentroid x: centroid from Naive Centroid algorithm base_NaiveCentroid_y: centroid from Naive Centroid algorithm base_SdssCentroid_x: centroid from Sdss Centroid algorithm base SdssCentroid y: centroid from Sdss Centroid algorithm base SdssCentroid xSigma: 1-sigma uncertainty on x position base SdssCentroid ySigma: 1-sigma uncertainty on y position base_SdssShape_xx: elliptical Gaussian adaptive moments base_SdssShape_yy: elliptical Gaussian adaptive moments base SdssShape xy: elliptical Gaussian adaptive moments base SdssShape xxSigma: 1-sigma uncertainty on xx moment base SdssShape yySigma: 1-sigma uncertainty on yy moment base_SdssShape_xySigma: 1-sigma uncertainty on xy moment base SdssShape x: elliptical Gaussian adaptive moments base SdssShape y: elliptical Gaussian adaptive moments

- fiat tools by Deep Lens Survey
- fiatfilter

ext_shapeHSM_HsmShapeRegauss_e1)**2+(ext _shapeHSM_HsmShapeRegauss_e2)**2<1.5 && deblend_nChild==0 && ext_shapeHSM_HsmShapeRegauss_flag==0 && base_CircularApertureFlux_12_0_flag==0 && base_SdssShape_xx+base_SdssShape_yy<200 && base_SdssShape_xx>1 && base_SdssShape_yy>1 && calib_psfUsed==0 && base_PixelFlags_flag_interpolatedCenter==0 && base_CircularApertureFlux_12_0_flux>14 && base_CircularApertureFlux_12_0_flux<300000

• fiatmap

hase SdesShane flux: elliptical Gaussian adaptive moments hase SdesShane fluxSigma: 1-sigma flux uncertainty hase SdesShane nef vy:

Results!

Name	Redshift[]	Diameter (arcmin)[6]
Abell 85	0.055061	2
Abell 2199	0.03051	182
Abell 119	0.0442	69







A85

Optical Image

I-filter mass map

G-filter mass map



-0.012

-0.0096

-0.0068

-0.0041

-0.0013

0.0015

0.0042

0.007

0.0097

A2199





-0.025

CFHT-I

-0.017

-0.0098

-0.0023

0.0053

0.013

0.02

0.02

-0.012

-0.0091

-0.0057

-0.0024







0.00096

0.0043

0.0076

0.011

0.0



Q&A

Acknowledgement

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Reference

[1] The Dark Matter Mystery: Gravitational Lensing

https://www.youtube.com/watch?v=7xKFrdzhM2Y

[2] Gravitational Lenisng: An Astrophysical Tool. Springer (2002).

[3] Massimo Meneghetti. Introduction to Gravitational Lensing: Lecture scripts.

[4] Large Synoptic Survey Telescope (LSST) Data Products Definition Document. (2017).

[5] https://en.wikipedia.org/wiki/Point_spread_function

[6] http://ned.ipac.caltech.edu/